Journal of Dynamic Systems, Measurement, and Control

Author Index

All authors of papers published in this volume are listed alphabetically. Full titles are included in each first author's entry. Letters in parentheses follow some of the page numbers: TB indicates Technical Brief, D indicates Discussion, E indicates Errata, and BR indicates Book Review.

Abbott, Jake J., and Okamura, Allison M. — Stable Forbidden-Region Virtual Fixtures for Bilateral Telemanipulation. **128**, 53–64

Agrawal, Sunil, Krovi, Venkat, and O'Malley, Marcia — Special Issue on Novel Robotics and Control. **128**, 1–2(ED)

Agrawal, Sunil K. — (see Pathak, Kaustubh) **128**, 104–111

Al-Dakkan, Khalid A., Barth, Eric J., and Goldfarb, Michael — Dynamic Constraint-Based Energy-Saving Control of Pneumatic Servo Systems. **128**, 655–662

Ambike, Ajit — (see Kim, Won-jong) **128**, 681–685(TB)

Ardema, Mark — (see Nguyen, Nhan) **128**, 946–959

Arimany, Gregor — (see Cai, Weihua) **128**, 820–828

Asgari, Jahan — (see Deur, Joško) **128**, 251–262

_____ (see Deur, Joško) **128**, 263–277

Bamba, Eiichi — (see Kosaka, Manabu) **128**, 746–749(TB)

Barreras, M. — (see Garcia-Sanz, M.) **128**, 319–329

Barth, Eric J. — (see Fite, Kevin B.) **128**, 159–164(TB)

_____ (see Al-Dakkan, Khalid A.) **128**, 655–662

_____ (see Shen, Xiangrong) **128**, 663–669

_____ (see Shields, Bobby L.) **128**, 999–1004(TB)

Barve, Jayesh J. — (see Paiuri, Nataraj S. V.) **128**, 400–405(TB)

Bazaei, Ali, and Majd, Vahid Johari — Neuro-Adaptive Friction Compensation for Single-Link Flexible Robots Using Serial-Gray-Box Modeling Strategy. **128**, 297–306

Behkam, Bahareh, and Sitti, Metin — Design Methodology for Biomimetic Propulsion of Miniature Swimming Robots. **128**, 36–43

Biediger, Erika — (see Singhose, William) **128**, 287–296

Bishop, Bradley E. — Control of Platoons of Nonholonomic Vehicles Using Redundant Manipulator Analogs. **128**, 171–175(TB)

Book, Wayne J. — (see Ching, Ho) **128**, 86–93

Bosgra, Okko — (see Gelder, Edgar de) **128**, 204–215

Bowling, Alan P. — Dynamic Performance, Mobility, and Agility of Multilegged Robots. **128**, 765–777

Bryant, Michael D. — (see Lee, Sanghoon) **128**, 584–591

Buckner, Gregory D., Choi, Heeju, and Gibson, Nathan S. — Estimating Model Uncertainty using Confidence Interval Networks: Applications to Robust Control. **128**, 626–635

Burton, Richard — (see Habibi, Saeid) **128**, 778–787

Cai, Weihua, Franco, Walfre, Arimany, Gregor, Sen, Mihir, Yang, K. T., and McClain, Rodney L. — Interaction Between Secondaries in a Thermal-Hydraulic Network. **128**, 820–828

Cao, M., Wang, K. W., DeVries, L., Fujii, Y., Tobler, W. E., and Pietron, G. M. — Experimental Characterization and Gray-Box Modeling of Spool-Type Automotive Variable-Force-Solenoid Valves With Circular Flow Ports and Notches. **128**, 636–654

Castillo-Toledo, B., Obregón-Pulido, G., and Espinosa-Guerra, O. — Structurally Stable Regulation for a Class of Nonlinear Systems: Application to a Rotary Inverted Pendulum. **128**, 922–928

Celentano, Laura, and Iervolino, Raffaele — New Results on Robot Modeling and Simulation. **128**, 811–819

Chang, Timothy, and Chen, Zhengfang — Reliable Decentralized Servomechanism Problem for Large-Scale Systems. **128**, 441–448(TB)

Chedjou, J. C., Kana, L. K., Moussa, I., Kyamakya, K., and Laurent, A. — Dynamics of a Quasiperiodically Forced Rayleigh Oscillator. **128**, 600–607

Chen, Jenq-Der — LMI Based to Robust Genetic Control Design for a Class of Uncertain Neutral Systems With State and Input Delays. **128**, 675–680(TB)

Chen, Zhengfang — (see Chang, Timothy) **128**, 441–448(TB)

Ching, Ho, and Book, Wayne J. — Internet-Based Bilateral Teleoperation Based on Wave Variable With Adaptive Predictor and Direct Drift Control. **128**, 86–93

Cho, Y. M. — (see Rajamani, R.) **128**, 718–721(TB)

Choi, Heeju — (see Buckner, Gregory D.) **128**, 626–635

Choo, Younseok, and Kim, Dongmin — SISO Continuous-System Reduction via Impulse Response Gramian by Iterative Formulae. **128**, 391–393(TB)

_____ Suboptimal Bilinear Routh Approximant for Discrete Systems. **128**, 742–745(TB)

Clapa, Damien J., Croft, Elizabeth A., and Hodgson, Antony J. — Equilibrium Point Control of a 2-DOF Manipulator. **128**, 134–141

Clark, Jonathan E., and Cutkosky, Mark R. — The Effect of Leg Specialization in a Biomimetic Hexapedal Running Robot. **128**, 26–35

Coe, Ian A. — (see Switkes, Joshua P.) **128**, 532–542

Cole, David J. — (see Pick, Andrew J.) **128**, 960–968

Colgate, J. Edward — (see Worsnopp, Tom) **128**, 44–52

Constantinescu, Daniela, Salcudean, Septimiu E., and Croft, Elizabeth A. — Haptic Manipulation of Serial-Chain Virtual Mechanisms. **128**, 65–74

Costello, Mark — (see Frost, Geoffrey) **128**, 1005–1012(TB)

Croft, Elizabeth A. — (see Constantinescu, Daniela) **128**, 65–74

_____ (see Clapa, Damien J.) **128**, 134–141

Cutkosky, Mark R. — (see Clark, Jonathan E.) **128**, 26–35

Cuzzola, Francesco A. — A Multivariable and Multi-Objective Approach for the Control of Hot-Strip Mills. **128**, 856–868

Gelder, Edgar de, Wal, Marc van de, Scherer, Carsten, Hol, Camile, and Bosgra, Okko — Nominal and Robust Feedforward Design With Time Domain Constraints Applied to a Wafer Stage. **128**, 204–215

de la Sen, M. — (see Ibeas, A.) **128**, 414–421(TB)

Deur, Joško, Asgari, Jahan, and Hrovat, Davor — Modeling and Analysis of Automatic Transmission Engagement Dynamics-Nonlinear Case Including Validation. **128**, 251–262

_____, **Asgari, Jahan, Hrovat, Davor, and Kovač, Petar** — Modeling and Analysis of Automatic Transmission Engagement Dynamics-Linear Case. **128**, 263–277

DeVries, L. — (see Cao, M.) **128**, 636–654

Dong, J., and Stori, J. A. — A Generalized Time-Optimal Bidirectional Scan Algorithm for Constrained Feed-Rate Optimization. **128**, 379–390

Doulgeri, Z., and Golfakis, A. — Nonlinear Manipulation Control of a

Compliant Object by Dual Fingers. **128**, 473–481
Dovifaaz, X. — (see Outbib, R.) **128**, 453–457(TB)

Ebert-Uphoff, Imme — (see Kozak, Kris) **128**, 731–736(TB)
Eitelberg, Eduard — On Multiloop Interaction and Relative and Bristol Gains. **128**, 929–937
Espinosa-Guerra, O. — (see Castillo-Toledo, B.) **128**, 922–928
Evans, Robert — (see Li, Yunfeng) **128**, 568–576

Fite, Kevin B., Mitchell, Jason E., Barth, Eric J., and Goldfarb, Michael — A Unified Force Controller for a Proportional-Injector Direct-Injection Monopropellant-Powered Actuator. **128**, 159–164(TB)
_____, **and Goldfarb, Michael** — Multivariable Loop-Shaping in Bilateral Telemanipulation. **128**, 482–488
Foglia, Mario M. — (see Reina, Giulio) **128**, 165–170(TB)
Formica, Domenico, Zollo, Loredana, and Guglielmelli, Eugenio — Torque-Dependent Compliance Control in the Joint Space for Robot-Mediated Motor Therapy. **128**, 152–158(TB)
Frakes, David — (see Khalid, Attir) **128**, 835–841
Franchek, Matthew A., Mohrfeld, Jackie, and Osburn, Andy — Transient Fueling Controller Identification for Spark Ignition Engines. **128**, 499–509
_____ (see Osburn, Andrew W.) **128**, 869–877
Franco, Walfre — (see Cai, Weihua) **128**, 820–828
Frost, Geoffrey, and Costello, Mark — Control Authority of a Projectile Equipped With an Internal Unbalanced Part. **128**, 1005–1012(TB)
Fujii, Y. — (see Cao, M.) **128**, 636–654

Garbini, Joseph L. — (see Kriewall, Thomas E.) **128**, 577–583
Garcia-Sanz, M., and Barreras, M. — Nondiagonal QFT Controller Design for a Three-Input Three-Output Industrial Furnace. **128**, 319–329
Gen, Matthew — (see O'Malley, Marcia K.) **128**, 75–85
Genin, Guy M., and Genin, Joseph — Sensor Placement for Angular Velocity Determination. **128**, 543–547
Genin, Joseph — (see Genin, Guy M.) **128**, 543–547
Gentile, Angelo — (see Reina, Giulio) **128**, 165–170(TB)
Georgiou, Helen M. S., and Mrad, Ridha Ben — Electromechanical Modeling of Piezoceramic Actuators for Dynamic Loading Applications. **128**, 558–567
Gerdes, J. Christian — (see Rossetter, Eric J.) **128**, 510–522
_____ (see Switkes, Joshua P.) **128**, 532–542
Ghodssi, Reza — (see Tan, Xiaobo) **128**, 891–898
Ghorbel, Fathi H. — (see Wang, Zhiyong) **128**, 142–151
Gibson, Nathan S. — (see Buckner, Gregory D.) **128**, 626–635
Gillespie, R. Brent, and Sövényi, Szabolcs — Model-Based Cancellation of Biodynamic Feedthrough Using a Force-Reflecting Joystick. **128**, 94–103
Goldfarb, Michael — (see Fite, Kevin B.) **128**, 159–164(TB)
_____ (see Fite, Kevin B.) **128**, 482–488
_____ (see Al-Dakkan, Khalid A.) **128**, 655–662
_____ (see Shen, Xiangrong) **128**, 663–669
_____ (see Shields, Bobby L.) **128**, 999–1004(TB)
Golfakis, A. — (see Doulgeri, Z.) **128**, 473–481
Gong, J. Q., and Yao, Bin — Output Feedback Neural Network Adaptive Robust Control With Application to Linear Motor Drive System. **128**, 227–235
Grizzle, Jessy W. — (see Lin, Chan-Chiao) **128**, 878–890
Guglielmelli, Eugenio — (see Formica, Domenico) **128**, 152–158(TB)
Guo, Xiaoxia — (see Ji, Zhijian) **128**, 696–700(TB)
Gupta, Abhishek — (see O'Malley, Marcia K.) **128**, 75–85
Güvenç, Bilin Aksun, and Güvenç, Levent — Robust Repetitive Controller Design in Parameter Space. **128**, 406–413(TB)
Güvenç, Levent — (see Güvenç, Bilin Aksun) **128**, 406–413(TB)

Habibi, Saeid — The Extended Variable Structure Filter. **128**, 341–351
_____, **Burton, Richard, and Sampson, Eric** — High Precision Hydrostatic Actuation Systems for Micro- and Nanomanipulation of Heavy Loads. **128**, 778–787
Harada, Kensuke, Nishiyama, Jun, Murakami, Yoshihiro, and Kaneko, Makoto — Pushing Manipulation for Multiple Objects. **128**, 422–427(TB)
Herman, Przemysław — Evaluation of Nonlinear Dynamics Using Optimal Motion Planning. **128**, 995–998(TB)
Hodgson, Antony J. — (see Clapa, Damien J.) **128**, 134–141
Hol, Camile — (see Gelder, Edgar de) **128**, 204–215
Horowitz, Roberto — (see Li, Yunfeng) **128**, 568–576
Hrovat, Davor — (see Deur, Joško) **128**, 251–262
_____ (see Deur, Joško) **128**, 263–277
Huang, Jeng-Tze — Parametric Identification for Second-Order Nonlinear Systems in Closed-Loop Operations. **128**, 686–690(TB)
Huey, John — (see Khalid, Attir) **128**, 835–841
Huissoon, Jan Paul — (see Karbasi, Hamidreza) **128**, 969–975(TB)
Huston, R. L. — (see Liu, C. Q.) **128**, 359–364

Ibeas, A., and de la Sen, M. — A Robustly Stable Multiestimation-Based Adaptive Control Scheme for Robotic Manipulators. **128**, 414–421(TB)
Ibrir, Salim — Convex Optimization Approach to Observer-Based Stabilization of Uncertain Linear Systems. **128**, 989–994(TB)
Iervolino, Raffaele — (see Celentano, Laura) **128**, 811–819
Inooka, Hikaru — (see Nankyo, Masanobu) **128**, 244–250
Ishihara, Tadashi — (see Nankyo, Masanobu) **128**, 244–250
Iwasaki, Tetsuya — (see Maslen, Eric H.) **128**, 197–203

Jacky, Jonathan P. — (see Kriewall, Thomas E.) **128**, 577–583
Jalics, Laci — (see Pisu, Pierluigi) **128**, 428–435(TB)
Jayasuriya, Suhada — (see Wu, Wei) **128**, 701–705(TB)
_____ (see Wu, Wei) **128**, 706–711(TB)
Ji, Kun — (see Kim, Won-jong) **128**, 681–685(TB)
Ji, Zhijian, Guo, Xiaoxia, Wang, Long, and Xie, Guangming — Robust H_∞ Control and Stabilization of Uncertain Switched Linear Systems: A Multiple Lyapunov Functions Approach. **128**, 696–700(TB)
Johnston, D. Nigel — Efficient Methods for Numerical Modeling of Laminar Friction in Fluid Lines. **128**, 829–834
Jun, Seung Kook, White, Glenn D., and Krovi, Venkat N. — Kinetostatic Design Considerations for an Articulated Leg-Wheel Locomotion Subsystem. **128**, 112–121

Kana, L. K. — (see Chedjou, J. C.) **128**, 600–607
Kaneko, Makoto — (see Harada, Kensuke) **128**, 422–427(TB)
Karbasi, Hamidreza, Khajepour, Amir, and Huissoon, Jan Paul — Unidrive Modular Robot: Dynamics, Control, and Experiments. **128**, 969–975(TB)
Karlapalem, Lalit — (see Lee, Sanghoon) **128**, 584–591
Kawato, Yusuke, and Kim, Won-jong — Multi-Degree-of-Freedom Precision Position Sensing and Motion Control Using Two-Axis Hall-Effect Sensors. **128**, 980–988(TB)
Kazerooni, H., and Steger, R. — The Berkeley Lower Extremity Exoskeleton. **128**, 14–25
_____ (see Uchimura, Yutaka) **128**, 914–921
Kelkar, Atul G. — (see Shi, Jianjun) **128**, 371–378
Kelly, Rafael — (see Moreno-Valenzuela, Javier) **128**, 670–674(TB)
Khajepour, Amir — (see Karbasi, Hamidreza) **128**, 969–975(TB)
Khalid, Attir, Huey, John, Singhose, William, Lawrence, Jason, and Frakes, David — Human Operator Performance Testing Using an Input-Shaped Bridge Crane. **128**, 835–841
Kim, Dongmin — (see Choo, Younseok) **128**, 391–393(TB)
Kim, Min-Joong — (see Lin, Chan-Chiao) **128**, 878–890
Kim, Won-jong, Ji, Kun, and Ambike, Ajit — Networked Real-Time Control Strategy Dealing With Stochastic Time Delays and Packet

Losses. **128**, 681–685(TB)
____ (see Kawato, Yusuke) **128**, 980–988(TB)
Kini, Ananth, Vincent, Thomas L., and Paden, Brad — The Bouncing Ball Apparatus as an Experimental Tool. **128**, 330–340
Kolmanovsky, Ilya, Polis, Michael P., and Sivergina, Irina F. — Identification of the Heat Flux in a Quasi-Static Thermoelastic System. **128**, 608–616
Kosaka, Manabu, Uda, Hiroshi, Bamba, Eiichi, and Shibata, Hiroshi — State-space Model Identification Using Input and Output Data With Steady State Values Zeroing Multiple Integrals of Output Error. **128**, 746–749(TB)
Kovač, Petar — (see Deur, Joško) **128**, 263–277
Kozak, Kris, Singhose, William, and Ebert-Uphoff, Imme — Performance Measures For Input Shaping and Command Generation. **128**, 731–736(TB)
Kriewall, Thomas E., Garbini, Joseph L., Sidles, John A., and Jacky, Jonathan P. — Heterodyne Digital Control of a High-Frequency Micromechanical Oscillator. **128**, 577–583
Krishnaswamy, Kailash, and Li, Perry Y. — Bond Graph Based Approach to Passive Teleoperation of a Hydraulic Backhoe. **128**, 176–185(TB)
Krovi, Venkat — (see Agrawal, Sunil) **128**, 1–2(ED)
Krovi, Venkat N. — (see Jun, Seung Kook) **128**, 112–121
Kuchenbecker, Katherine J., and Niemeyer, Günter — Induced Master Motion in Force-Reflecting Teleoperation. **128**, 800–810
Kulakowski, Bohdan — (see Xiao, Jie) **128**, 523–531
Kyamakya, K. — (see Chedjou, J. C.) **128**, 600–607

Lam, James — (see Wang, Qing) **128**, 394–399(TB)
Laurent, A. — (see Chedjou, J. C.) **128**, 600–607
Lawrence, Jason — (see Khalid, Attir) **128**, 835–841
Léchevin, N., and Rabbath, C. A. — Sampled-data Control of a Class of Nonlinear Flat Systems With Application to Unicycle Trajectory Tracking. **128**, 722–728(TB)
Lee, Ho-Hoon, Liang, Yi, and Segura, Del — A Sliding-Mode Antisway Trajectory Control for Overhead Cranes With High-Speed Load Hoisting. **128**, 842–845
Lee, Hyeongcheol — Reliability Indexed Sensor Fusion and Its Application to Vehicle Velocity Estimation. **128**, 236–243
Lee, Sanghoon, Bryant, Michael D., and Karlapalem, Lalit — Model- and Information Theory-Based Diagnostic Method for Induction Motors. **128**, 584–591
Lew, Jae — (see Wu, Jianhua) **128**, 788–799
Li, Fang — (see Liu, C. Q.) **128**, 359–364
Li, Perry Y. — (see Krishnaswamy, Kailash) **128**, 176–185(TB)
Li, Yanfang — (see O'Malley, Marcia K.) **128**, 75–85
Li, Yangmin, and Liu, Yugang — Real-Time Tip-Over Prevention and Path Following Control for Redundant Nonholonomic Mobile Modular Manipulators via Fuzzy and Neural-Fuzzy Approaches. **128**, 753–764
Li, Yunfeng, Marcassa, Federico, Horowitz, Roberto, Oboe, Roberto, and Evans, Robert — Track-Following Control With Active Vibration Damping of a PZT-Actuated Suspension Dual-Stage Servo System. **128**, 568–576
Liang, Yi — (see Lee, Ho-Hoon) **128**, 842–845
Lin, Chan-Chiao, Kim, Min-Joong, Peng, Huei, and Grizzle, Jessy W. — System-Level Model and Stochastic Optimal Control for a PEM Fuel Cell Hybrid Vehicle. **128**, 878–890
Lin, Psang Dain, and Sung, Chi-Kuen — Camera Calibration Based on Snell's Law. **128**, 548–557
Liu, C. Q., Li, Fang, and Huston, R. L. — Dynamics of a Basketball Rolling Around the Rim. **128**, 359–364
Liu, Yugang — (see Li, Yangmin) **128**, 753–764
Lu, Shin-Wen — (see Yeh, T.-J.) **128**, 189–196
Lynch, Kevin — (see Worsnopp, Tom) **128**, 44–52

Ma, O. — (see Weber, M.) **128**, 307–318
Majd, Vahid Johari — (see Bazaei, Ali) **128**, 297–306
Marcassa, Federico — (see Li, Yunfeng) **128**, 568–576
Maslen, Eric H., Montie, Dominick T., and Iwasaki, Tetsuya — Robustness Limitations in Self-Sensing Magnetic Bearings. **128**, 197–203
Matunaga, Saburo — (see Singhose, William) **128**, 287–296
Mavroidis, C. — (see Vitrani, M. A.) **128**, 216–226
McClain, Rodney L. — (see Cai, Weihua) **128**, 820–828
Milella, Annalisa — (see Reina, Giulio) **128**, 165–170(TB)
Mills, James K. — (see Ren, Lu) **128**, 976–979(TB)
Minor, Mark A. — (see Zhu, Xiaorui) **128**, 489–498
Misawa, Eduardo A. — (see Richter, Hanz) **128**, 729–730(TB)
Mitchell, Jason E. — (see Fite, Kevin B.) **128**, 159–164(TB)
Modafe, Alireza — (see Tan, Xiaobo) **128**, 891–898
Mohrfeld, Jackie — (see Franchek, Matthew A.) **128**, 499–509
Montagner, Vinícius F., and Peres, Pedro L. D. — State Feedback Gain Scheduling for Linear Systems With Time-Varying Parameters. **128**, 365–370
Montie, Dominick T. — (see Maslen, Eric H.) **128**, 197–203
Morel, G. — (see Vitrani, M. A.) **128**, 216–226
Moreno-Valenzuela, Javier, and Kelly, Rafael — A Hierarchical Approach to Manipulator Velocity Field Control Considering Dynamic Friction Compensation. **128**, 670–674(TB)
Moussa, I. — (see Chedjou, J. C.) **128**, 600–607
Mrad, Ridha Ben — (see Georgiou, Helen M. S.) **128**, 558–567
Mukherjee, Ranjan — (see Nudehi, Shahin) **128**, 278–286
Murakami, Yoshihiro — (see Harada, Kensuke) **128**, 422–427(TB)
Musil, Milos — Localization and Quantification of Breathing Crack. **128**, 458–462(TB)

Nankyo, Masanobu, Ishihara, Tadashi, and Inooka, Hikaru — Feedback Control of Braking Deceleration on Railway Vehicle. **128**, 244–250
Nguang, Sing Kiong, and Shi, Peng — Robust $\mathcal{H}_\infty$ Output Feedback Control Design for Takagi-Sugeno Systems with Markovian Jumps: A Linear Matrix Inequality Approach. **128**, 617–625
Nguyen, Nhan, and Ardema, Mark — Optimality of Hyperbolic Partial Differential Equations With Dynamically Constrained Periodic Boundary Control—A Flow Control Application. **128**, 946–959
Niemeyer, Günter — (see Kuchenbecker, Katherine J.) **128**, 800–810
Nikitczuk, J. — (see Vitrani, M. A.) **128**, 216–226
Nishiyama, Jun — (see Harada, Kensuke) **128**, 422–427(TB)
Nudehi, Shahin, Mukherjee, Ranjan, and Shaw, Steven W. — Active Vibration Control of a Flexible Beam Using a Buckling-Type End Force. **128**, 278–286

Oboe, Roberto — (see Li, Yunfeng) **128**, 568–576
Obregón-Pulido, G. — (see Castillo-Toledo, B.) **128**, 922–928
Okada, Hideto — (see Singhose, William) **128**, 287–296
Okamura, Allison M. — (see Abbott, Jake J.) **128**, 53–64
O'Malley, Marcia — (see Agrawal, Sunil) **128**, 1–2(ED)
O'Malley, Marcia K., Gupta, Abhishek, Gen, Matthew, and Li, Yanfang — Shared Control in Haptic Systems for Performance Enhancement and Training. **128**, 75–85
Osburn, Andrew W., and Franchek, Matthew A. — Reducing Engine Idle Speed Deviations Using the Internal Model Principle. **128**, 869–877
Osburn, Andy — (see Franchek, Matthew A.) **128**, 499–509
Ouladsine, M. — (see Outbib, R.) **128**, 453–457(TB)
Outbib, R., Dovifaaz, X., Rachid, A., and Ouladsine, M. — A Theoretical Control Strategy for a Diesel Engine. **128**, 453–457(TB)

Paden, Brad — (see Kini, Ananth) **128**, 330–340
Pagilla, Prabhakar R. — (see Zhu, Yongliang) **128**, 691–695(TB)

____ (see Zhu, Yongliang) **128**, 712–717(TB)
Paluri, Nataraj S. V., and Barve, Jayesh J. — A Reliable Algorithm to Compute the Spectral Set of a Polytope of Polynomials to Prescribed Accuracy. **128**, 400–405(TB)
Papadopoulos, Evangelos — (see Vartholomeos, Panagiotis) **128**, 122–133
Park, Sungyong — (see Zhu, Xiaorui) **128**, 489–498
Patel, K. — (see Weber, M.) **128**, 307–318
Pathak, Kaustubh, and Agrawal, Sunil K. — Band-Limited Trajectory Planning and Tracking for Certain Dynamically Stabilized Mobile Systems. **128**, 104–111
Peng, Huei — (see Lin, Chan-Chiao) **128**, 878–890
Peres, Pedro L. D. — (see Montagner, Vinícius F.) **128**, 365–370
Peshkin, Michael — (see Worsnopp, Tom) **128**, 44–52
Pick, Andrew J., and Cole, David J. — Measurement of Driver Steering Torque Using Electromyography. **128**, 960–968
Pietron, G. M. — (see Cao, M.) **128**, 636–654
Pisu, Pierluigi, Serrani, Andrea, You, Song, and Jalics, Laci — Adaptive Threshold Based Diagnostics for Steer-By-Wire Systems. **128**, 428–435(TB)
Polis, Michael P. — (see Kolmanovsky, Ilya) **128**, 608–616

Rabbath, C. A. — (see Léchevin, N.) **128**, 722–728(TB)
Rachid, A. — (see Outbib, R.) **128**, 453–457(TB)
Rajamani, R., and Cho, Y. M. — An Upper Bound on the Maximum Stability Radius Achievable by State Feedback. **128**, 718–721(TB)
Reina, Giulio, Foglia, Mario M., Milella, Annalisa, and Gentile, Angelo — Visual and Tactile-Based Terrain Analysis Using a Cylindrical Mobile Robot. **128**, 165–170(TB)
Reinhall, Per G. — (see Smithwick, Quinn Y. J.) **128**, 899–913
Ren, Lu, Mills, James K., and Sun, Dong — Adaptive Synchronized Control for a Planar Parallel Manipulator: Theory and Experiments. **128**, 976–979(TB)
Richter, Hanz, and Misawa, Eduardo A. — Boundary Layer Eigenvalues in SISO Discrete-Time Sliding Mode Control with Observer. **128**, 729–730(TB)
Rossetter, Eric J., and Gerdes, J. Christian — Lyapunov Based Performance Guarantees for the Potential Field Lane-keeping Assistance System. **128**, 510–522
____ (see Switkes, Joshua P.) **128**, 532–542

Salcudean, Septimiu E. — (see Constantinescu, Daniela) **128**, 65–74
Sampson, Eric — (see Habibi, Saeid) **128**, 778–787
Scherer, Carsten — (see Gelder, Edgar de) **128**, 204–215
Segura, Del — (see Lee, Ho-Hoon) **128**, 842–845
Seibel, Eric J. — (see Smithwick, Quinn Y. J.) **128**, 899–913
Sen, Mihir — (see Cai, Weihua) **128**, 820–828
Serrani, Andrea — (see Pisu, Pierluigi) **128**, 428–435(TB)
Sharf, I. — (see Weber, M.) **128**, 307–318
Shaw, Steven W. — (see Nudehi, Shahin) **128**, 278–286
Shen, Tielong — (see Zhou, Di) **128**, 592–599
Shen, Xiangrong, Zhang, Jianlong, Barth, Eric J., and Goldfarb, Michael — Nonlinear Model-Based Control of Pulse Width Modulated Pneumatic Servo Systems. **128**, 663–669
Sheng, Ye, and Tomizuka, Masayoshi — Intelligent Modeling of Thrust Force in Drilling Process. **128**, 846–855
Shi, Jianjun, Kelkar, Atul G., and Soloway, Don — Stable Reconfigurable Generalized Predictive Control With Application to Flight Control. **128**, 371–378
Shi, Peng — (see Nguang, Sing Kiong) **128**, 617–625
Shibata, Hiroshi — (see Kosaka, Manabu) **128**, 746–749(TB)
Shields, Bobby L., Barth, Eric J., and Goldfarb, Michael — Predictive Control for Time-Delayed Switching Control Systems. **128**, 999–1004(TB)
Sidles, John A. — (see Kriewall, Thomas E.) **128**, 577–583
Singhose, William, Biediger, Erika, Okada, Hideto, and Matunaga, Saburo — Experimental Verification of Real-Time Control for Flexible Systems With On-Off Actuators. **128**, 287–296
____ (see Kozak, Kris) **128**, 731–736(TB)
____ (see Khalid, Attir) **128**, 835–841
Sitti, Metin — (see Behkam, Bahareh) **128**, 36–43
Sivergina, Irina F. — (see Kolmanovsky, Ilya) **128**, 608–616
Smithwick, Quinn Y. J., Vagners, Juris, Reinhall, Per G., and Seibel, Eric J. — An Error Space Controller for a Resonating Fiber Scanner: Simulation and Implementation. **128**, 899–913
Soloway, Don — (see Shi, Jianjun) **128**, 371–378
Southward, Steve C. — (see Tran, Chau M.) **128**, 449–452(TB)
Sövényi, Szabolcs — (see Gillespie, R. Brent) **128**, 94–103
Steger, R. — (see Kazerooni, H.) **128**, 14–25
Stori, J. A. — (see Dong, J.) **128**, 379–390
Sun, Dong — (see Ren, Lu) **128**, 976–979(TB)
Sung, Chi-Kuen — (see Lin, Psang Dain) **128**, 548–557
Surgenor, Brian W. — (see Wang, Zhonghua) **128**, 436–440(TB)
Switkes, Joshua P., Rossetter, Eric J., Coe, Ian A., and Gerdes, J. Christian — Handwheel Force Feedback for Lanekeeping Assistance: Combined Dynamics and Stability. **128**, 532–542

Tamura, Katsutoshi — (see Zhou, Di) **128**, 592–599
Tan, Xiaobo, Modafe, Alireza, and Ghodssi, Reza — Measurement and Modeling of Dynamic Rolling Friction in Linear Microball Bearings. **128**, 891–898
Tobler, W. E. — (see Cao, M.) **128**, 636–654
Tomizuka, Masayoshi — (see Sheng, Ye) **128**, 846–855
Tran, Chau M., and Southward, Steve C. — A Sensor Placement Strategy for the Hybrid Adaptive Feedforward Observer. **128**, 449–452(TB)
Treesatayapun, C., and Uatrongjit, S. — Controlling Chaos by Hybrid System Based on FREN and Sliding Mode Control. **128**, 352–358

Uatrongjit, S. — (see Treesatayapun, C.) **128**, 352–358
Uchimura, Yutaka, and Kazerooni, H. — A μ-Synthesis Based Control for Compliant Maneuvers. **128**, 914–921
Uda, Hiroshi — (see Kosaka, Manabu) **128**, 746–749(TB)
Upadhyay, Devesh, and Van Nieuwstadt, Michiel — Model Based Analysis and Control Design of a Urea-SCR deNOx Aftertreatment System. **128**, 737–741(TB)

Vagners, Juris — (see Smithwick, Quinn Y. J.) **128**, 899–913
Valdivia y Alvarado, Pablo, and Youcef-Toumi, Kamal — Design of Machines With Compliant Bodies for Biomimetic Locomotion in Liquid Environments. **128**, 3–13
van de Wal, Marc — (see Gelder, Edgar de) **128**, 204–215
Van Nieuwstadt, Michiel — (see Upadhyay, Devesh) **128**, 737–741(TB)
Vartholomeos, Panagiotis, and Papadopoulos, Evangelos — Dynamics, Design and Simulation of a Novel Microrobotic Platform Employing Vibration Microactuators. **128**, 122–133
Vincent, Thomas L. — (see Kini, Ananth) **128**, 330–340
Vitrani, M. A., Nikitczuk, J., Morel, G., Mavroidis, C., and Weinberg, B. — Torque Control of Electrorheological Fluidic Resistive Actuators for Haptic Vehicular Instrument Controls. **128**, 216–226

Wang, K. W. — (see Cao, M.) **128**, 636–654
Wang, Long — (see Ji, Zhijian) **128**, 696–700(TB)
Wang, Qing, Lam, James, Xu, Shengyuan, and Zhang, Liqian — Delay-Dependent γ-Suboptimal H_∞ Model Reduction for Neutral Systems With Time-Varying Delays. **128**, 394–399(TB)
Wang, Zhiyong, and Ghorbel, Fathi H. — Control of Closed Kinematic Chains Using A Singularly Perturbed Dynamics Model. **128**, 142–151
Wang, Zhonghua, and Surgenor, Brian W. — A Problem With the LQ Control of Overhead Cranes. **128**, 436–440(TB)

Weber, M., Patel, K., Ma, O., and Sharf, I. — Identification of Contact Dynamics Model Parameters From Constrained Robotic Operations. **128**, 307–318
Weinberg, B. — (see Vitrani, M. A.) **128**, 216–226
White, Glenn D. — (see Jun, Seung Kook) **128**, 112–121
Williams, Robert L., II — (see Wu, Jianhua) **128**, 788–799
Worsnopp, Tom, Peshkin, Michael, Lynch, Kevin, and Colgate, J. Edward — Controlling the Apparent Inertia of Passive Human-Interactive Robots. **128**, 44–52
Wu, Jianhua, Williams, Robert L., II, and Lew, Jae — Velocity and Acceleration Cones for Kinematic and Dynamic Constraints on Omni-Directional Mobile Robots. **128**, 788–799
Wu, Ting-Ying — (see Yeh, T.-J.) **128**, 189–196
Wu, Wei, and Jayasuriya, Suhada — Design of Feedback Systems With Plant Input Rate Saturation via QFT Approach. **128**, 701–705(TB)
____, and Jayasuriya, Suhada — Design for Feedback Systems With Plant Input Amplitude and Rate Saturation. **128**, 706–711(TB)

Xiao, Jie, and Kulakowski, Bohdan — Hybrid Genetic Algorithm: A Robust Parameter Estimation Technique and its Application to Heavy Duty Vehicles. **128**, 523–531
Xie, Guangming — (see Ji, Zhijian) **128**, 696–700(TB)
Xu, Li — (see Yao, Bin) **128**, 938–945
Xu, Shengyuan — (see Wang, Qing) **128**, 394–399(TB)

Yang, K. T. — (see Cai, Weihua) **128**, 820–828
Yaniv, O. — Automatic Loop Shaping of MIMO Controllers Satisfying Sensitivity Specifications. **128**, 463–471
Yao, Bin — (see Gong, J. Q.) **128**, 227–235
____, and Xu, Li — Output Feedback Adaptive Robust Control of Uncertain Linear Systems With Disturbances. **128**, 938–945
Yeh, T.-J., Lu, Shin-Wen, and Wu, Ting-Ying — Modeling and Identification of Hysteresis in Piezoelectric Actuators. **128**, 189–196
You, Song — (see Pisu, Pierluigi) **128**, 428–435(TB)
Youcef-Toumi, Kamal — (see Valdivia y Alvarado, Pablo) **128**, 3–13

Zhang, Jianlong — (see Shen, Xiangrong) **128**, 663–669
Zhang, Liqian — (see Wang, Qing) **128**, 394–399(TB)
Zhou, Di, Shen, Tielong, and Tamura, Katsutoshi — Adaptive Nonlinear Synchronization Control of Twin-Gyro Precession. **128**, 592–599
Zhu, Xiaorui, Minor, Mark A., and Park, Sungyong — Distributed Robust Control of Compliant Framed Wheeled Modular Mobile Robots. **128**, 489–498
Zhu, Yongliang, and Pagilla, Prabhakar R. — Adaptive Estimation of Time-Varying Parameters in Linearly Parametrized Systems. **128**, 691–695(TB)
____, and Pagilla, Prabhakar R. — Adaptive Controller and Observer Design for a Class of Nonlinear Systems. **128**, 712–717(TB)
Zollo, Loredana — (see Formica, Domenico) **128**, 152–158(TB)